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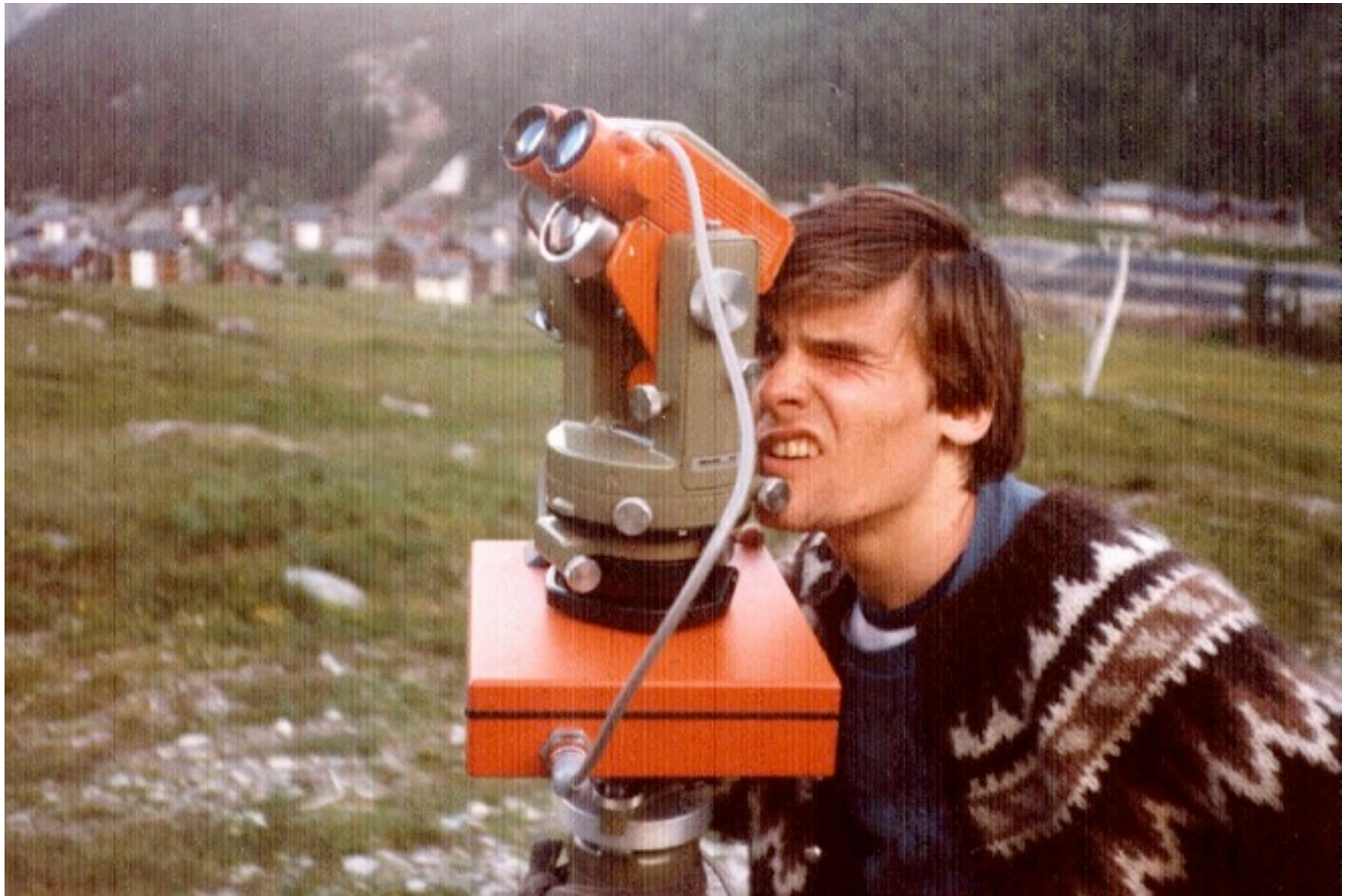
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Ontology of Observations in Space and Time

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as of Nov 1: UCSB Center for Spatial Studies





Some Problems to Solve

1. sensor networks are often **disconnected** from the web
 - true: bus locations, water quality, agricultural data, ...
 - false: weather, traffic, food, ...
2. even if they are connected, or with observations in general, it is hard to
 - **interpret** somebody else's observations
 - **abstract** over sensor observations (aggregate, generalize)
 - link sensor data to **process** models
3. sensor **standards** emphasize technology and syntax, not information and semantics of observations.



Missing: Support to find data and reason about sensed phenomena

- Reference Use Cases of W3C:
 - A. Device discovery: **find device(s)** that meet given criteria
 - B. Data discovery: **find data** meeting certain criteria (e.g. temporal and spatial constraints)
 - C. Process/provenance: Describe and exploit information about how the data has been or can be collected to support other operations like **composition of resources** or diagnostics

- Today, we can at best deal with A, because
 - ...standards treat sensing as a technical rather than an information process
 - ...we lack ontologies of many sensed phenomena
 - ...both hinders reasoning with sensor data (e.g. event reasoning)



A Human Sensor Example



"Is this a meadow, a field,
or a vacant lot?"

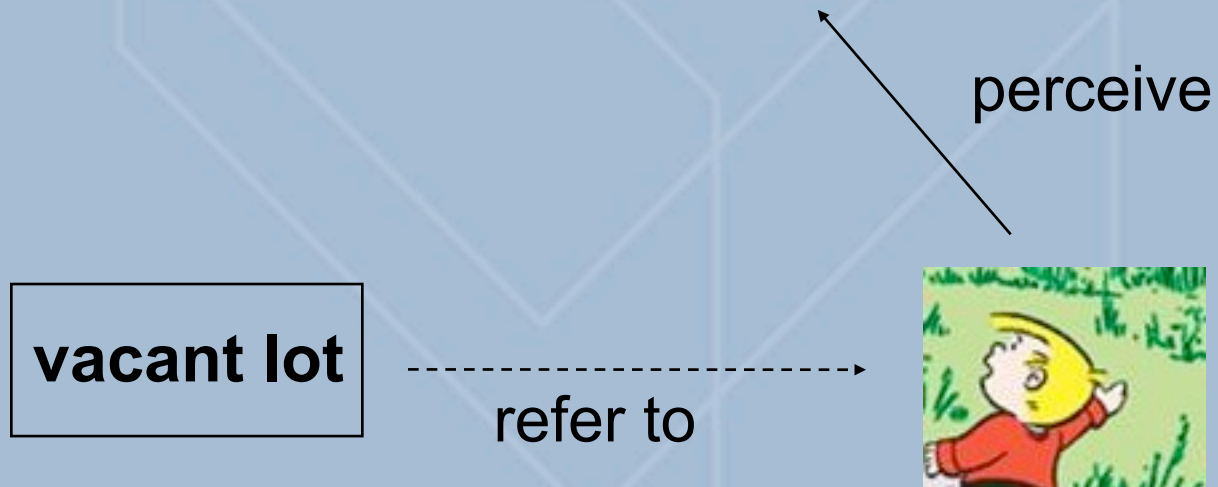
Sensing as Information Process

vacant lot

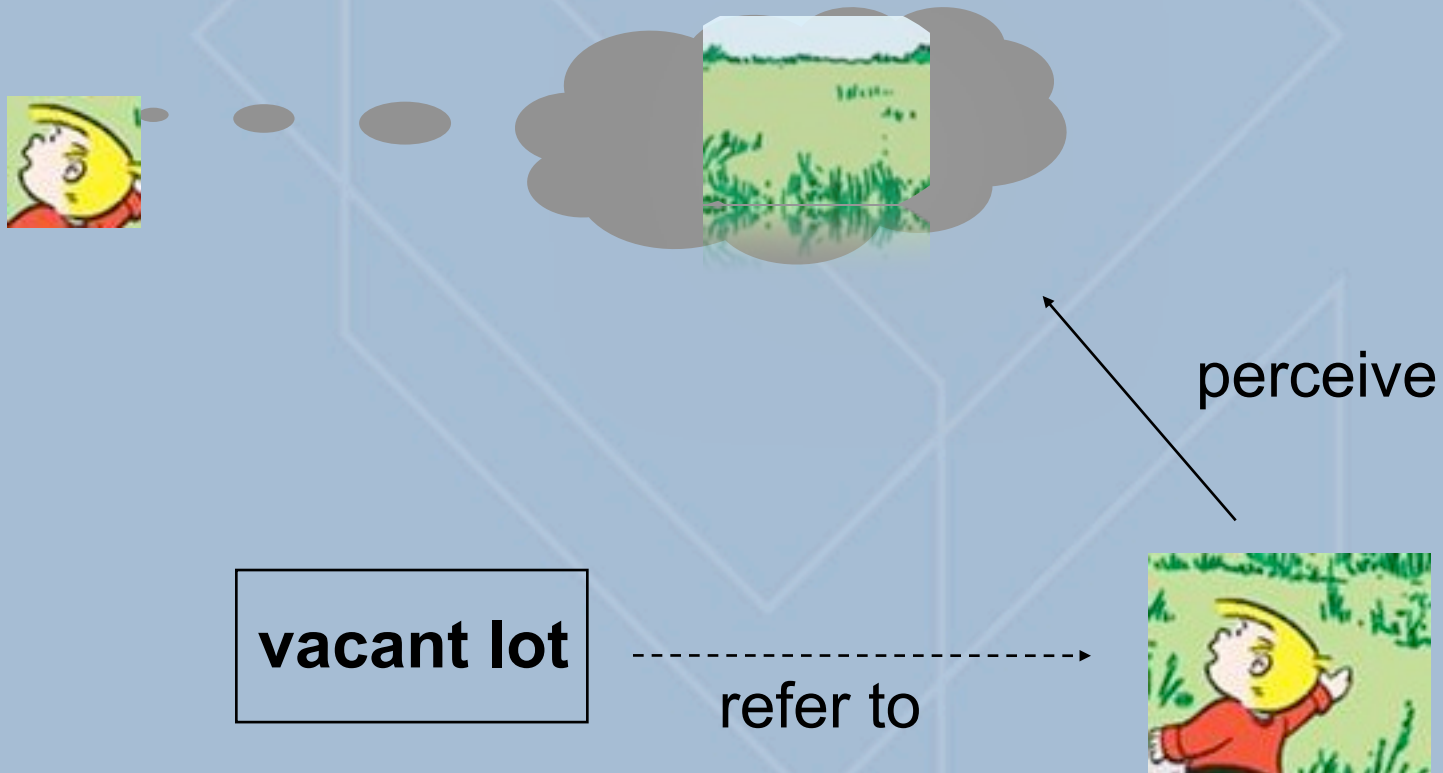
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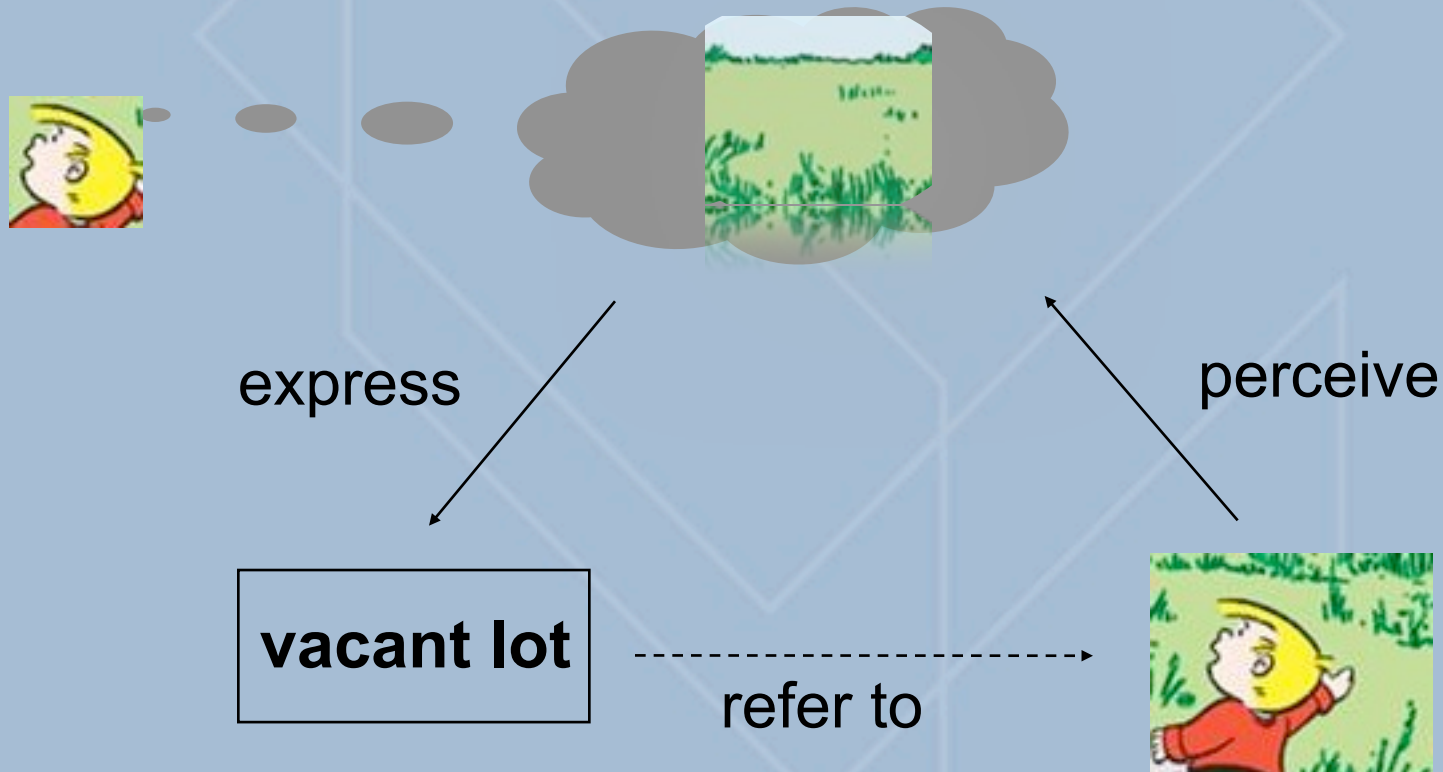
Sensing as Information Process



Sensing as Information Process



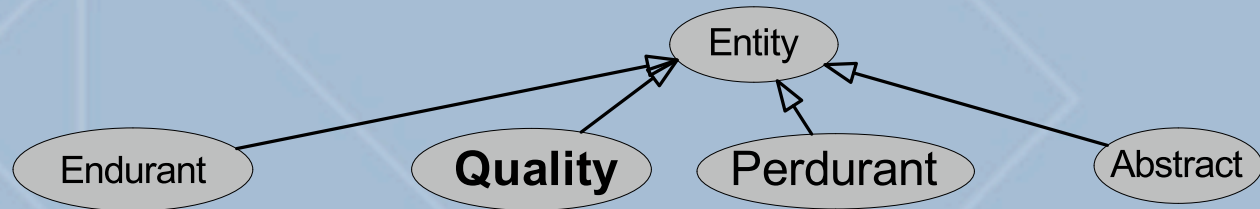
Sensing as Information Process



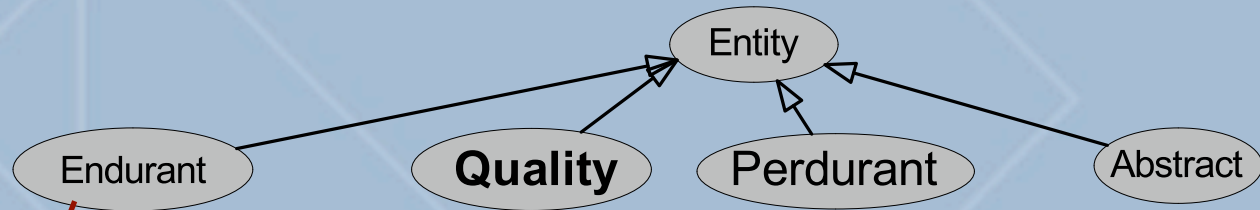
Structuring Observations with DOLCE



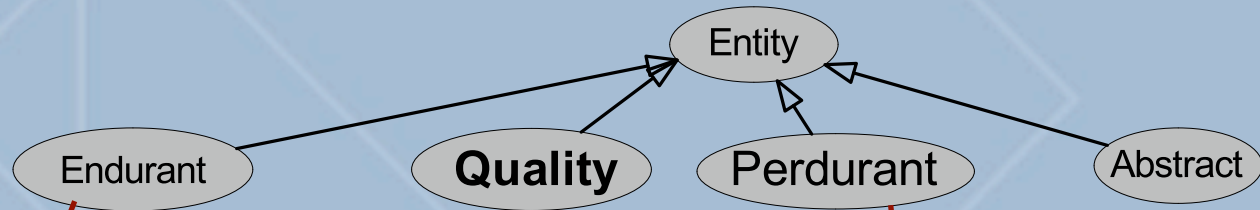
Structuring Observations with DOLCE



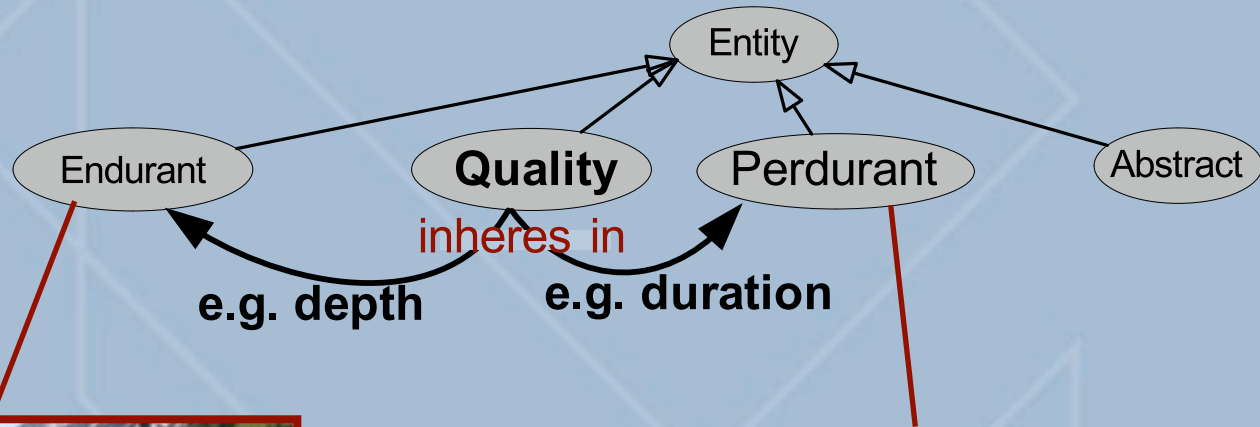
Structuring Observations with DOLCE



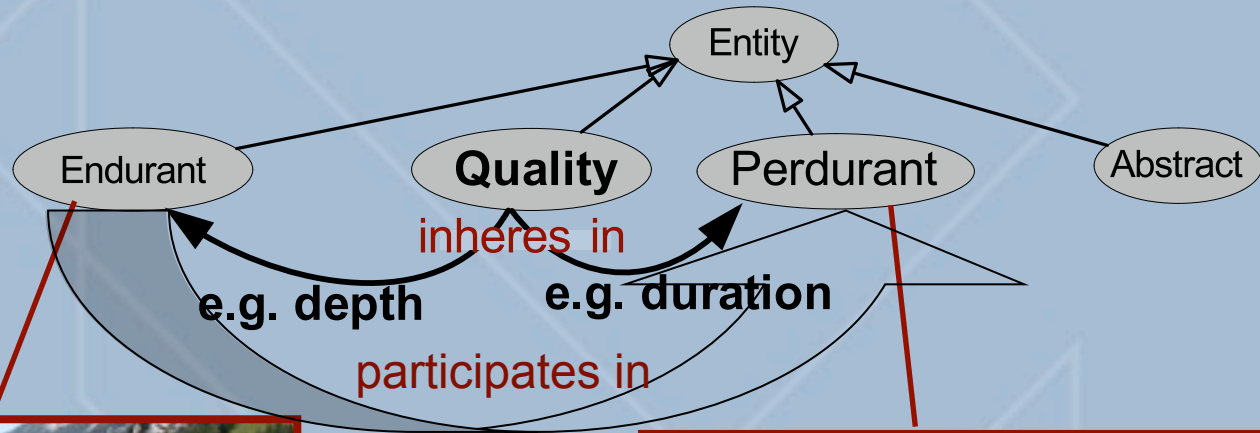
Structuring Observations with DOLCE



Structuring Observations with DOLCE

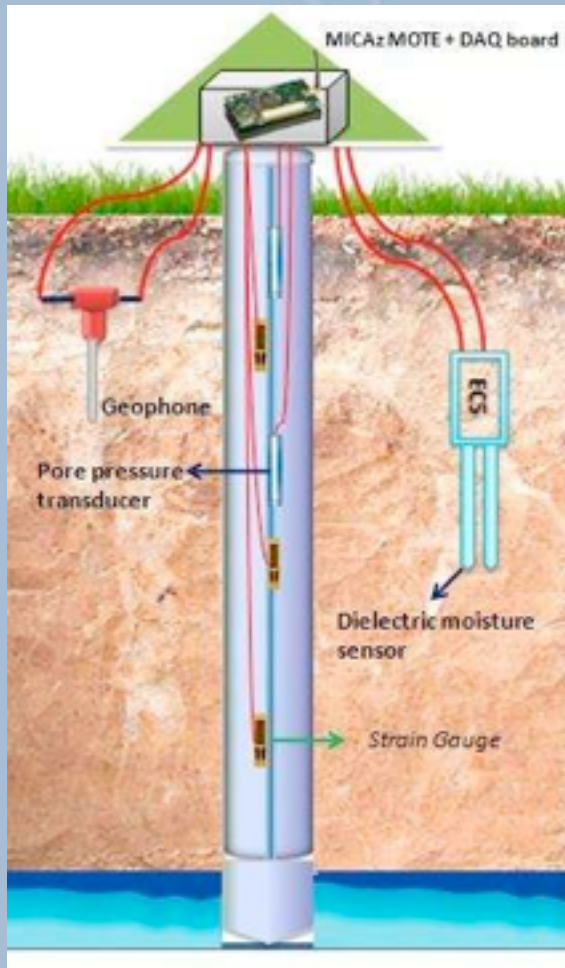


Structuring Observations with DOLCE



Observation as an Information Process

“An Observation is an action with a result which has a value describing some phenomenon” [OGC]



It assigns symbols to qualities of endurants or perdurants.

We have produced a generic **observation ontology**, abstracting from sensor technology and focusing on **information processes**

[see Kuhn 2009, GeoS proceedings]



The Functional Ontology of Observation and Measurement (FOOM)

1. commits to **DOLCE**'s four top level categories
2. uses DOLCE's notion of quality spaces and its extension by reference **spaces** [Probst]
3. clarifies OGC sensor standards **terminology**
phenomenon: observable quality (of endurant, perdurant, or quality)
feature of interest: endurant or perdurant
4. generalizes sensors to include **humans, animals**
in fact, it generalizes human observations to include technical ones
5. generalizes qualities to include **affordances** [Ortmann]
6. written as **an algebraic specification** and simulation in Haskell.



Qualities

Qualities are what agents **perceive**.

DOLCE provides the notion of quality and reference **spaces** [Gärdenfors, Masolo, Probst].

The class of all quality types (= properties) is modelled as a constructor class in Haskell:

```
class QUALITIES quality entity
```

```
instance QUALITIES Temperature AmountOfAir
```

```
instance QUALITIES Humidity AmountOfAir
```

```
instance QUALITIES Height Step
```

```
...
```



Stimuli

Stimuli (“detectable changes”) are **perdurants**.



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```
class (QUALITIES quality entity, APOS agent)
=> STIMULI quality entity agent where
    perceive :: quality entity -> agent -> agent
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Stimuli

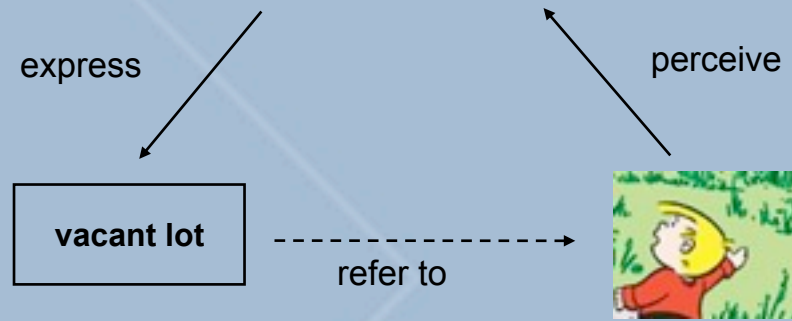
Stimuli (“detectable changes”) are **perdurants**.

```
class (QUALITIES quality entity, APOS agent)
  => STIMULI quality entity agent where
    perceive :: quality entity -> agent -> agent

instance STIMULI Temperature AmountOfAir Person where
  perceive (Temperature amountOfAir) person =
    person {pQuale = heat amountOfAir}
```

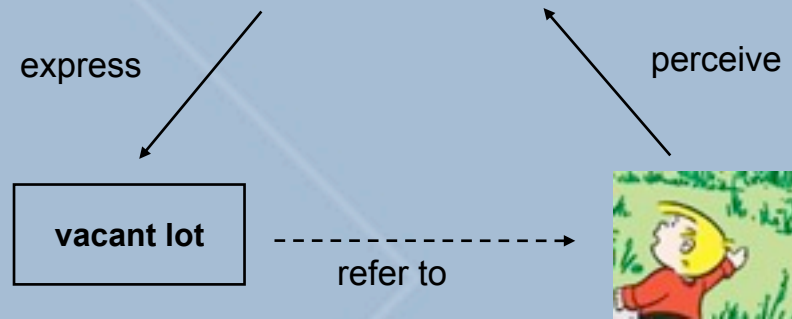


Observations



To observe is to **perceive** a quality and then **express** the quale.

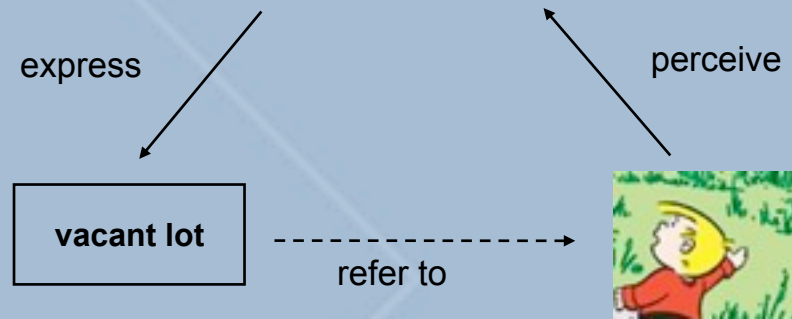
Observations



To observe is to **perceive** a quality and then **express** the quale.

```
class (STIMULI quality entity agent)
  => OBSERVATIONS quality entity agent where
    observe :: quality entity -> agent -> agent
```


Observations



To observe is to **perceive** a quality and then **express** the quale.

class (STIMULI quality entity agent)

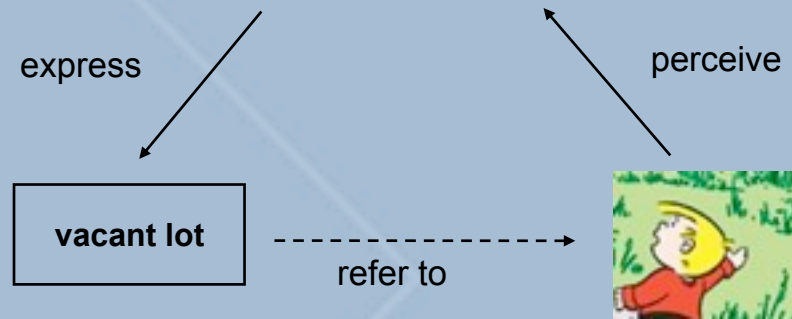
=> OBSERVATIONS quality entity agent **where**

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instance OBSERVATIONS Temperature AmountOfAir Person **where**



Observations



To observe is to **perceive** a quality and then **express** the quale.

class (STIMULI quality entity agent)

=> OBSERVATIONS quality entity agent **where**

observe :: quality entity -> agent -> agent

instance OBSERVATIONS Temperature AmountOfAir Person **where**

observe (Temperature amountOfAir) person =

person {pValue = if (pQuale (perceive (Temperature amountOfAir) person)) > 15 then "warm" else "cold"}.



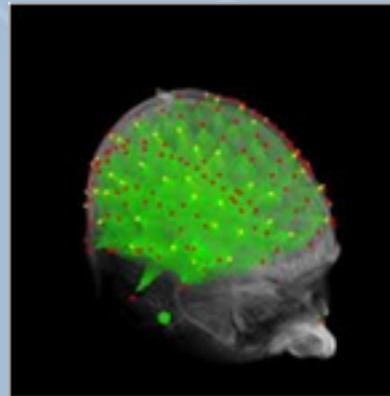
Some Findings

1. **stimuli** and qualia get “abstracted away”
no need to specify them, but they are the glue of the ontology
2. qualities and their bearers (endurants, perdurants) are human **constructions**
3. interoperability requires storing minimal constructions
then make abstractions explicit
4. **linked data** with ontology design patterns provide the right modeling flexibility
5. Think big about observations!
e.g., genomes as observations of trajectories of species



Images as Observations

1. coverage functions $\mathbf{x} \rightarrow \mathbf{z}$ (left total)
2. treat as single observations (of fields) or as aggregates of observations
3. interpret as images of objects, surfaces, events
4. distinguish **spatially intensive** from spatially **extensive** observables (fields vs objects)
5. **boundaries** are enemies of semantic interoperability



Ongoing and Future Work

1. model spatial and temporal **granularity and accuracy**
simple: quality-bearing endurants define spatial granularity
sophisticated: spatio-temporal convolution
2. model the **thematic** granularity
as part of a semantic datum
3. compute semantic **datum transformations**
4. extend to **social** qualities
trust and reputation
5. treat **position and time** as observables
simple: the endurants and perdurants bearing observed qualities
sophisticated: support, containment, path, before ... relations
6. specify **perception-action cycles** with sensors and actuators
use them to calibrate semantics of observations.



Conclusions

- Sensors are *the* future source of data
 - especially if including humans (and animals) as sensors
 - but current standards treat them as a technology, rather than as an information source (the “aboutness” is missing)
- The FOOM sensor observation ontology addresses semantic issues
 - **qualities** inhere in **endurants** and **perdurants**
 - **stimuli** carry signals to the sensor
 - semantic **datums** translate signals to values
- OGC Semantic Enablement Service connects FOOM to Spatial Data Infrastructures
- W3C incubator connects it to the Semantic Sensor Web.



NEW CUYAMA

Population 562

Ft. above sea level 2150

Established 1951

TOTAL 4663

Thank You! Questions?

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<http://musil.uni-muenster.de/>

<http://spatial.ucsb.edu/>

<http://www.ogcnetwork/swe>

<http://sensorweb.uni-muenster.de>

<http://www.w3.org/2005/Incubator/ssn/XGR-ssn-20110628/>

http://geog.ucsb.edu/~jano/SSN-XG_SensorOntology.pdf

Kuhn, W., 2009. A Functional Ontology of Observation and Measurement. K. Janowicz, M. Raubal, and S. Levashkin (Eds.): *GeoSpatial Semantics · Third International Conference (GeoS 2009), Mexico City, 3-4 December 2009*. Springer-Verlag Lecture Notes in Computer Science 5892: 26–43.

The FOOM ontology in Haskell is currently under revision

